

MANTA M8P V2.0 User Manual



Revision Log

Version	Date	Revisions
v1.00	20th August 2023	Initial Version

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Product Profile

BIGTREETECH Manta M8P V2.0 is a 32-bit 3D printer control board designed for use with Klipper firmware. It allows direct installation of a core board to run Klipper, greatly simplifying connections to a Raspberry Pi and saving space in the electronics enclosure. The board has a BTB socket for use with a CM4, CB1, or other solutions, providing flexibility beyond the expensive CM4.

Feature Highlights

- · Uses a 32-bit STM32H723ZET6 ARM Cortex-M7 MCU running at 550MHz.
- The TPS5450-5A power chip supports 12/24V DC input and delivers up to 5A/6A peak for powering a Raspberry Pi.
- A BOOT button is provided for DFU firmware updates.
- The thermistor circuit is protected to prevent MCU damage from shorted heated bed and heater cartridge connections.
- PWM fans support 24/12/5V voltage selection without external transformer module, reducing failure points.
- The thermistor resistor can select the pull-up resistor value through a jumper to support PT1000 without an external module, which is convenient for customers to use for DIY purposes.
- The MCU firmware can be upgraded through an SD card or through the "make flash" command in Klipper to update the MCU firmware via DFU.
- The BTB connector allows use of CM4, CB1, or other core boards.
- The onboard TMC driver works in SPI and UART modes, and the onboard DIAG function pin can be used by simply plugging in a jumper.
- Connectors for filament sensor, auto power-off, BLTouch, RGB, I2C, servo, 5V power detection, etc.
- High performance MOSFETs reduce heating.
- Replaceable fuses for easy service.
- 3x 4-pin fan headers usable for water cooling.
- Proximity switch header supports NPN and PNP (24/12/5V).
- · SPI expansion for accelerometer-based resonance compensation.

Specifications

Overall Dimensions	170 x 102.7mm
Installation Dimensions	Please refer to BIGTREETECH MANTA M8P V2.0 -SIZE-top.pdf
Microprocessor	ARM Cortex-M7 STM32H723ZET6 550MHz
Driver Input Voltage	24V, HV (24-60V) Selectable
Board Input Voltage	VIN=DC12V or DC24V
Heated Bed Input Voltage	BED IN=DC12V or DC24V
Logic Voltage	DC3.3V
Heating Interfaces	Heated Bed (HB), Heater Cartridge (HE0, HE1, HE2, HE3)
Max Heated Bed Output	
Current	10A, peak 10.5A
Max Heater Cartridge	
Output Current	5.5A, peak 6A
	5x 2-pin PWM fans (FAN0, FAN1, FAN2, FAN3,
Con Interfaces	FAN4, PI FAN), $2x 4$ -pin PWM fans (FAN5, FAN6),
Fair Interfaces	TX always off fail, FAINU, FAINT, FAINZ, FAINS, EANIA EANIS EANIS are available with $5/12/24V$
	selections
Max Fan Output Current	1A neak 1 1A
Total Current for Heater	
Cartridge + Driver + Fans	Less than 12A
¥	BLTouch (Servos, Probe), Servo, Filament Sensor,
Expansion Interfaces	5V Power Loss Detection, PS-ON, I2C, RGB, SPI,
	TFT, EXP, CAN etc.
	Supports TMC5160, TMC2209, TMC2225,
Motor Drivers	TMC2226, TMC2208, TMC2130, ST820, LV8729,
	DRV8825, A4988 etc.
Driver Modes	SPI, UART, STEP/DIR
Motor Interfaces	Motor1, Motor2, Motor3 (dual), Motor4, Motor5,
Tomporaturo Soncor	
Interfaces	5x 100K NTC, 4x support NTC and PT1000
Display Interfaces	SPI touchscreen I CD display
PC Communication	
	USB 2.0*3 LAN DSL CSL SPL 40-pin GPLO
Function Interfaces	HDMI0/HDMI1. SOC-Card. MCU-Card
Supported Machine Types	Cartesian, Delta, Kossel, Ultimaker, CoreXY
Recommended Software	Cura, Simplify3D, Pronterface, Repetier-host, Makerware

Dimensions



Peripheral Interfaces

Interface Diagram





BIGTREE TECH MANTA M8P V2.0 Pin-Out

8

Interface Introduction

USB Power Supply

After powering on the M8P, the LED on the bottom left corner will light up to indicate normal power supply. The VUSB jumper in the center is for selecting power - it should only be shorted when powering the board via USB or supplying power out via USB.



Stepper Motor Drivers

Standard STEP/DIR (STANDALONE) Mode

For drivers like A4988, DRV8825, LV8729, ST820, etc, use a jumper to short MS0-MS2 based on the microstepping table.



Note: A4988 and DRV8825 require RST and SLP jumpered for proper operation.

Driver Chip	MODE 2	MODE 1	MODE 0	Microsteps	Excitation Mode
DRV8825	L	L	L	Full Step	2 Phase
Max 32	L	L	Н	1/2	1-2 Phase
microsteps,8.2V	L	Н	L	1/4	W1-2 Phase
-45V 2.5A at	L	Н	Н	1/8	

24V T=25°C	Н	L	L	1/16	
	Н	L	Н	1/32	
	Н	Н	L	1/32	
	Н	Н	Н	1/32	
Drive Current Formula R _{ISENSE} =0.1Ω	I _{CHOP} =	$\frac{\mathbf{V}_{(\mathbf{xREF})}}{5 * \mathbf{R}_{ISEI}}$) NSE		
Driver Chip	MS1	MS2	MS3	Microsteps	Excitation Mode
	L	L	L	Full Step	2 Phase
A4988 May 16	Н	L	L	1/2	1-2 Phase
microstops 25V	L	Н	L	1/4	W1-2 Phase
	Н	Н	L	1/8	2W1-2 Phase
	Н	Н	Н	1/16	4W1-2 Phase
Drive Current Formula \mathbf{R}_{S} =0.1 Ω	I _{TripMAX}	$= \frac{\mathbf{V}_{\mathbf{REF}}}{8 * \mathbf{R}_{S}}$	-		

Driver Chip	MD3	MD2	MD1	Microsteps	Excitation Mode
	L	L	L	Full Step	2 Phase
	L	L	Н	1/2	1-2 Phase
LV8729	L	Н	L	1/4	W1-2 Phase
Max 128	L	Н	Н	1/8	2W1-2 Phase
microsteps, 36V	Н	L	L	1/16	4W1-2 Phase
1.8A	Н	L	Н	1/32	8W1-2 Phase
	Н	Н	L	1/64	16W1-2 Phase
	Н	Н	Н	1/128	32W1-2 Phase
Drive Current					
Formula	$I_{OUT} = (V_{REF} / 5) / RF1$				
RF1=0.22Ω		-			

Driver Chip	MS3	MS2	MS1	Microsteps
	L	L	L	Full Step
	L	L	Н	1/2
ST820	L	Н	L	1/4
Max 256	L	Н	Н	1/8
microsteps, 45V	Н	L	L	1/16
1.5A	Н	L	Н	1/32
	Н	Н	L	1/128
	Н	Н	Н	1/256
Drive Current		Vara Var		
Formula	I _{peak} =		<u>)</u>	
Rs=0.15Ω	F · · · · ·	5 * K _S		

TMC Drivers - UART Mode

For TMC2208, TMC2209, TMC2225, etc, short the jumper for each as shown in the red box. Microsteps and current are configured in firmware.



TMC Drivers - SPI Mode

For example, TMC2130, TMC5160, TMC5161, etc. Each uses four jumpers to short the red box positions in the diagram. Micro-stepping and drive current are set through the firmware.



TMC Drivers - DIAG (Sensorless Homing)

For sensorless homing, insert the jumper as shown. Remove when not in use - no need to cut the DIAG pin of the driver.



Driver Voltage Selection





Installing a Core Board on the BTB Connector

M8P+CM4: Note orientation as shown below.



M8P+CB1: Note orientation as shown below.



CNC Fan Voltage Selection

Set the output voltage to 5V, 12V, or 24V using jumpers. Note: Before selecting the voltage, please make sure to confirm the supported voltage of the fan. Our company is not responsible for fan damage caused by incorrect voltage selection.



100K NTC or PT1000 Settings

For 100K NTC thermistors, no jumper is needed. At this time, the pull-up resistor of TH0-TH3 is 4.7K 0.1%. For PT1000, short the pins in the red box to add 4.12K 0.1% in parallel, at this time, the pull-up resistor of TH0-TH1 is 2.2K (Note: The temperature accuracy read using this method will be lower than MAX31865.)



BLTouch Wiring



Auto Power Off (Relay V1.2) Wiring



MINI12864 V2.0 Wiring



RGB Wiring



Servo Wiring



I2C Wiring (Temperature and Humidity Sensor)





DSI and CSI Connections

Proximity Switch Wiring

Normally open (NPN), no jumper needed, e.g. 24V:





Normally closed (PNP), short jumper, e.g. 24V:

CNC fan function, short jumper, e.g. 24V:



4-Pin Fan / Water Cooling Connection

(24V example below)



SysCooling

Using the Raspberry Pi CM4

Download OS Image

When using CM4, download the image of Fluidd, Mainsail directly, also, you can download a pure OS image from the Raspberry Pi official website and and install it yourself.

Fluidd: <u>https://github.com/fluidd-core/FluiddPl/releases</u>

Mainsail: https://github.com/mainsail-crew/MainsailOS/releases

Official Raspberry Pi OS Image: <u>https://www.raspberrypi.com/software/operating-systems</u> (Note: CM4 has some differences from Pi 3B/4B, refer to the system configuration section to enable USB, DSI etc.)

Raspberry Pi OS

Our recommended operating system for most users.

Compatible with:

All Raspberry Pi models

Raspberry Pi OS with desktop Release date: January 28th 2022

System: 32-bit Kernel version: 5.10 Debian version: 11 (bullseye) Size: 1.246Mg Show SHA256 file integrity hash: Release notes

Di OC with desliter and recommended officiar

Download

Download torrent

Archive

Raspberry Pi OS with desktop and recommended software



Download and install Raspberry Pi Imager

Download and install the official Raspberry Pi burning software: <u>https://www.raspberrypi.com/software/</u>

Write OS

CM4 LITE Version (MicroSD Card)

- 1. Insert MicroSD into your computer via a card reader.
- 2. Choose OS.



3. Select "Use custom", then select the image that you downloaded.

🍯 Ras	pberry Pi In	nager v1.7.2	- 🗆	×
		Operating System	x	
	÷	Emulation and game OS Emulators for running retro-computing platforms	>	
	<u>[0]</u>	Other specific-purpose OS Thin clients, digital signage and 3D printing operating systems	>	
	Ŋ	Misc utility images Bootloader EEPROM configuration, etc.	>	
	Ō	Erase Format card as FAT32		
	.img	Use custom Select a custom .img from your computer		



4. Click the settings icon in the lower right corner.

5. "Enable SSH" and then click "Save", there are other functions that can be set in this interface, please modify them according to your needs. Details are as follows:

Set hostname: raspberrypi.local // custom hostname, default is raspberrypi.local

Enable SSH

Set username and password // custom username and password, default username: pi, password: raspberry

Configure wireless LAN // custom WiFi name and password

	Advanced options	X
Image customization option	for this session only	•
Set hostname: ^{MS}	q-pi . local	
Enable SSH		
Use password	authentication	
Allow public-k	ey authentication only	
Set authorized	d_keys for 'msq':	
Catulaarnana and n		
	SAVE	

6. Select the MicroSD card and click "WRITE" (WRITE the image will format the MicroSD card. Be careful not to select the wrong storage device, otherwise the data will be formatted).



7. Wait for the process to complete.

😽 Raspberry	Pi Imager v1.7.2	_		×
	Write Successful	x		
	2022-04-04-raspios-bullseye-armhf.img.xz has been written to RPi-MSD- 0001			
	You can now remove the SD card from the reader			
202	CONTINUE			
		Ę	3	
		Ę	Ş	

CM4 eMMC Version

Note: eMMC version will not run the system in the Micro SD card.

1. Install rpiboot

For Windows: <u>http://github.com/raspberrypi/usbboot/raw/master/win32/rpiboot_setup.exe</u> For Mac and Linux: <u>https://github.com/raspberrypi/usbboot#building</u>

2. Toggle switches 4 (USBOTG) and 3 (RPIBOOT) to ON to enter BOOT mode.



- 3. Connect the Type-C to the computer's USB port (to avoid problems caused by insufficient computer USB power supply, it is recommended to use an external 24V power supply for the motherboard), run **sudo** ./rpiboot(Mac/Linux) or rpiboot.exe on Windows, and then the CM4 eMMC will be recognized as a large-capacity storage device by the computer (if rpiboot reports an error at this time, you can try unplugging and re-plugging the USB).
- 4. Use the Raspberry Pi Imager software to write the OS image. The steps are exactly the same as the LITE version.
- After the writing is completed, power off and toggle switches 4 (USBOTG) and 3 (RPIBOOT) back to OFF. After powering on again, it will enter the normal working mode.

System Settings (CM4)

USB 2.0 Hub Port

MANTA M8P has a USB 2.0 Hub. To save power, the USB port of the CM4 is disabled by default. To enable it, add the following content to the config.txt file: dtoverlay=dwc2,dr_mode=host

DSI1 Display

The default display interface is HDMI. The DSI interface of the MANTA M8P is DSI1. To use it, download the DSI1 driver by entering the following command: **sudo wget** <u>https://datasheets.raspberrypi.com/cmio/dt-blob-disp1-cam1.bin -O/boot/dt-blob.bin</u>

After downloading this driver and restarting, the screen on the DSI interface can be displayed normally. If you want to use the HDMI interface, delete the downloaded **/boot/dt-blob.bin** driver and restart, then HDMI can output normally.

CSI1 Camera

The DSI1 driver downloaded in **DSI1 Display** also includes the CSI1 driver. If you don't want to install the DSI1 driver and only want to install the CSI1 driver, find the driver you want to use at <u>https://datasheets.raspberrypi.com/licence.html</u> download it to the CM4's boot folder, and rename it to **dt-blob.bin**, then refer to the settings here for use:

https://projects.raspberrypi.org/en/projects/getting-started-with-picamera/

Using the **BIGTREETECH CB1**

Download OS Image

When using CB1, use the provided image: https://github.com/bigtreetech/CB1/releases

Download and install Raspberry Pi Imager

Download and install the official Raspberry Pi writing software: <u>https://www.raspberrypi.com/software/</u> The CB1 OS image can also be written using this software.

Write OS

- 1. Insert MicroSD into your computer via a card reader.
- 2. Choose OS.



3. Select "Use custom", then select the image that you downloaded.

🍯 Ras	pberry Pi In	nager v1.7.2		×
		Operating System	x	
	÷	Emulation and game OS Emulators for running retro-computing platforms	>	
	0	Other specific-purpose OS Thin clients, digital signage and 3D printing operating systems	>	
	Ŋ	Misc utility images Bootloader EEPROM configuration, etc.	>	
	Ō	Erase Format card as FAT32		
	.img	Use custom Select a custom .img from your computer		

4. Select the MicroSD card and click "WRITE" (WRITE the image will format the MicroSD card. Be careful not to select the wrong storage device, otherwise the data will be formatted).



5. Wait for the writing to complete.



Set up WiFi

Note: If you are using an Ethernet connection, please skip this step.

CB1 cannot directly use the Raspberry Pi Imager software to set up Wi-Fi name and password like CM4. After the OS image is burned, there will be a FAT32 partition recognized by the computer on the MicroSD card. In this partition, there is a configuration file named "system.cfg".

BOOT (J:)			~	ē
へ 名称	修改日期	类型	大小	
dtb	2022/11/9 2:50	文件夹		
dtb-5.16.17-sun50iw9	2022/11/9 2:50	文件夹		
📙 gcode	2022/11/9 10:35	文件夹		
next	2022/11/9 2:50	NEXT 文件		0 KB
BoardEnv.txt	2022/11/9 2:53	文本文档		1 KB
📾 boot.bmp	2022/11/9 2:52	BMP 图像	1	0 KB
💿 boot.cmd	2022/11/9 2:48	Windows 命令脚本		4 KB
📧 boot.scr	2022/11/9 2:53	屏幕保护程序		4 KB
config-5.16.17-sun50iw9	2022/11/9 2:39	17-SUN50IW9	17	6 KB
📄 Image	2022/11/9 2:39	文件	20,63	1 KB
initrd.img-5.16.17-sun50iw9	2022/11/9 2:54	17-SUN50IW9	9,17	1 KB
system.cfg	2022/11/10 17:52	文本文档		1 KB
System.map-5.16.17-sun50iw9	2022/11/9 2:39	17-SUN50IW9	4,23	9 KB
📄 ulnitrd	2022/11/9 2:54	文件	9,17	1 KB
vmlinuz-5.16.17-sun50iw9	2022/11/9 2:39	17-SUN50IW9	20,63	1 KB

Edit in Notepad and set WIFI-SSID and PASSWORD.

Configure the Motherboard

Connect to the Device Using SSH Software

- 1. Install the SSH software Mobaxterm: https://mobaxterm.mobatek.net/download-home-edition.html
- 2. Insert the MicroSD card into the MANTA M8P and power it on. Wait for the system to start, which takes about 1-2 minutes.
- 3. After the device is connected to Wi-Fi or an Ethernet cable, it will be automatically assigned an IP address.
- 4. Enter the router management interface to find the device's IP address.



5. Alternatively, use the tool <u>https://angryip.org/</u> to scan all IP addresses in the current local area network and reorder them by hostname. Find the device with the hostname Fluidd, Mainsail, or BTT-CB1, as shown in the image below.

, IP范围 - Angry IP So	canner			—	×
扫描转到命令收藏	缺工具	帮助			
IP范围: 192.168.1.0	到	192.168.1.255 IP范围 🗸 🗘			
主机名: XTZJ-20211206	JC IP†	子网掩码 ∨ ▶ 开始 ☷			
IP	Ping	主机名 ^	端口 [3+]		^
🔗 192.168.1.107	71 室秒	fluiddpi.local	80		
\varTheta 192.168.1.106	0 毫秒	XTZJ-20211206JC.DHCP HOST	80,443		
🔗 192.168.1.1	8 毫秒	[n/a]	80		
🕞 192.168.1.100	5000	[n/a]	[n/a]		
9192.168.1.101	4999	[n/a]	[n/a]		

6. Open the installed Mobaxterm software, click "Session", click "SSH" in the pop-up window, enter the device's IP address in the "Remote host" input box, and click "OK" (Note: The computer and the device must be on the same

💐 MobaXterm	- 0	\times
Terminal Sessions View X server Tools Games Settings Macros Help	V	
Session Servers Tools Games Sessions View Split MultiExec Tunneling Packages Settings Help	X server	Exit
Quick connect		Ø
Les ressions Session settings	×	- 22
WISL-Default WISL-Default WISL-Default 2 SSH Telnet Rsh Xdmcp RDP VNC FTP STP Serial File SH Port	WSL	-
Advanced SSr settings Terminal settings Doukthalk settings		

 Enter the login name and password to access the SSH terminal interface. CM4:

Login name: pi Password: raspberry CB1:

Login name: biqu Password: biqu



local area network).

Compile MCU Firmware

1. After connecting to the device via SSH, enter the following command in the command line:

cd ~/klipper/

make menuconfig

Use the following configuration to compile the firmware (if the options below are not available, please update the Klipper firmware source code to the latest version):

- * [*] Enable extra low-level configuration options
- * Micro-controller Architecture (STMicroelectronics STM32) --->
- * Processor model (STM32H723) --->
- * Bootloader offset (128KiB bootloader (SKR SE BX v2.0)) --->
- * Clock Reference (25 MHz crystal) --->
- * Communication interface (USB (on PA11/PA12)) --->

(Top)

	net ppe	- I Trumber - contragora	
[*]	Enable extra low-level co Micro-controller Architec Processor model (STM32H72 Bootloader offset (128KiB Clock Reference (25 MHz c Communication interface (USB ids>	nfiguration options ture (STMicroelectro 3)> bootloader (SKR SE B rystal)> USB (on PA11/PA12))	nics STM32)> BX v2.0))> >
()	GPIO pins to set at micro	-controller startup	
[Spa [0]	ace/Enter] Toggle/enter Ouit (prompts for save)	[?] Help [ESC] Leave menu	[/] Search

- 2. After completing the configuration selection, enter `q` to exit the configuration interface. When asked if you want to save the configuration, select "Yes".
- Enter make to compile the firmware. After the make command is executed, the klipper.bin firmware we need will be generated in the device's home/pi/klipper/out folder. You can download it directly to your computer

usi	ng tł	ne S	SH	sof	twa	re.						
I 19	2.168.1.107										- 0	×
Termin	al Session	is View	X server	Tools	Games	Settings	Macros	Help				
			**	+			•	++	4	**	0 X	C
Sessio	Servers	Tools	Games	Sessions	View	Solit	MultiExec		Package	s Settinas	Help X server	Exit
Ouic	k connec	t									(A) Y TOL 1 931 C	ID
Quic	K connee											
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	home/pi/klipper	/out/) c	ompiling	out/src/neopixel.o	
20	 Name 			Size (K	B) La	st modified	Owner	(Gre C	ompiling	out/src/pulse_counter.o	
0	t									ompiling	out/src/stm32/watchdog.o	
1	src				20	22-03-08	pi	1	x C	ompiling	out/src/stm32/clockline.o	
10	lib				20	22-03-08	pi	F	xi C	ompiling	out/src/generic/crc16_ccitt.o	
	board-	eneric			20	22-03-08	pi	F	a C	ompiling	out/src/generic/armcm_boot.o	
	📄 klipper.	elf		1635	20	22-03-08	pi	¢	a C	ompiling	out/src/generic/armcm_irq.o	
	klipper.	dict		6	20	22-03-08	pi	ş		ompiling	out/src//lib/stm32h7/system_stm32h7xx.o	
	klipper.	bin		23	20	22-03-08	pi		i c	ompiling	out/src/stm32/stm32h7.o	
	compile [2]	_time_requ	est.txt	Onen	~				- C	ompiling	out/src/generic/armcm_timer.o	
	compile	_time_requ	iest.o	Open	th defaul	t tout adita	-		C	ompiling	out/src/stm32/gpioperiph.o	
	compile	_time_requ	iest.d	Open wi		t text edito	•		C	ompiling	out/src/stm32/stm32h7_adc.o	
	Compile	_time_requ	est.c	Open wi	un					ompiling	out/src/stm32/usbota.o	
	board-	пк		Open wi	th defaul	t program.			č	ompiling	out/src/stm32/chipid.o	
	Doard		-	Compar	e file with	1			C	ompiling	out/src/generic/usb_cdc.o	
	II autocoi		*	Downloa	d				C	ompiling	out/src/stm32/hard_pwm.o	
	ς			Delete					B	uilding	out/compile_time_request.o	
			2	Rename					P	reproces	sing out/src/generic/armcm link.ld	
									— i	inking o	ut/klipper.elf	
				Copy file	e path				C	reating	hex file out/klipper.bin	
				Copy file	e path to	terminal (N	/iddle mo	use click)	10	τιυισαρι	:~/Klupper \$	~

Update Firmware

SD Card Update

- Rename `klipper.bin` to "firmware.bin", copy it to the root directory of the SD card, insert the SD card into the MANTA M8P SD card slot, press the reset button or power on again, and the firmware will be automatically updated. After the update is complete, the "firmware.bin" in the SD card will be renamed to "FIRMWARE.CUR".
- 2. Enter Is /dev/serial/by-id/ in the command line to query the mainboard's ID and confirm whether the firmware has been successfully burned. If the burning is successful, a Klipper device ID will be returned, as shown in the image below.



Copy and save this ID, as it needs to be set in the configuration file.

DFU Update

If you can find the MCU's Klipper device ID using **Is /dev/serial/by-id/**, you can directly enter

make flash FLASH_DEVICE= /dev/serial/by-id/usb-

Klipper_stm32h712xx_41003D001751303232383230-if00

to burn the firmware (Note: Replace /dev/serial/by-id/xxx with the actual ID found in the previous step).



After the burning is completed, there will be a dfu-util: **Error during download get_status** error message, which can be ignored.

Configure Klipper

 Enter the Raspberry Pi's IP address in the computer's browser to access it. Download the reference configuration named generic-bigtreetech-mantam8p-V2_0.cfg in the path shown in the image below. If you cannot find this file, please update the Klipper firmware source code to the latest version or download it from GitHub:

https://github.com/bigtreetech/Manta-M8P

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ЭD	G-CODE VIEWER	Current pa	th: /config_examples		Free disk: 25.1 GB
Ð	HISTORY		Name 🛧	Filesize	Last modified
٩			printer-wanhao-duplicator-i3-v2.1-2017.cfg	5.0 kB	2023年1月12日 11:15
			sample-aliases.cfg	5.8 kB	2023年1月12日 11:15
			sample-bigtreetech-ebb-canbus-v1.0.cfg	1.4 kB	2023年1月12日 11:15
	<u></u>		sample-bigtreetech-ebb-canbus-v1.1.cfg	1.5 kB	2023年1月12日 11:15

2. Upload the mainboard configuration file to Configuration Files.

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> CONSOLE	i) Config Files	Upload File	~
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G-CODE FILES		(
3D G-CODE VIEWER	Current path: /config		Free disk: 25.1 GB
FG HISTORY	□ Name ↑	Filesize	Last modified
	□ Name ↑ □ □ theme	Filesize —	Last modified 1970年1月20日 16:51
	Name ↑ .theme .moonraker.conf.bkp	Filesize 1.5 kB	Last modified 1970年1月20日 16:51 2023年1月12日 11:07
	Name ↑ .theme .moonraker.conf.bkp .rowsnest.conf	Filesize - 1.5 kB 1.8 kB	Last modified 1970年1月20日 16:51 2023年1月12日 11:07 2023年1月4日 13:07

3. Add the mainboard configuration in the "printer.cfg" file:

[include generic-bigtreetech-manta-m8p-V2_0.cfg]

- 4. Modify the ID number in the configuration file to the actual ID of the mainboard.
- Follow the instructions in the link below to configure the specific functions of the mainboard: https://www.klipper3d.org/Overview.html

V2.0 Upgrade Notes

- Upgraded MCU to ARM Cortex-M7 STM32H723ZET6 550MHz.
- · Added interfaces: servo, I2C, 5V detection, TFT expansion ports.
- Changed EXP1+EXP2 to FPC connectors.
- Increased USB output current.
- Added large-capacity energy storage capacitors to the 5V circuit, especially at the core board 5V input port, to prevent the 5V supply from breaking due to excessive current during CM4 startup.
- Upgraded 12V power supply for increased capacity and resistance.

Precautions

- Power off before connecting/disconnecting anything except USB, HDMI and Ethernet. Includes enabling eMMC flashing.
- Pay attention to the heat dissipation issues of CM4 and CB1. If the running application consumes excessive system resources, it can lead to significant heating.

If you need further resources for this product, you can find them at [GitHub](https://github.com/bigtreetech/). If you cannot find what you need, you may contact our after-sales support(service005@biqu3d.com).

If you encounter any other problems during use or have suggestions or feedback, please contact us. Thank you for choosing BIGTREETECH products.